In re Appln. of KIMATA et al. Application No. Unassigned

10/530720 Aeg 6/2/08

SPECIFICATION AMENDMENTS

Replace the paragraph beginning at page 2, line 12 with:

With reference to Figs. 2 and 32A to 3B, details of the surge voltage occurring at the cable connection ends of the motor 2 are described. Figs. 2 and 32A to 3B are drawings that depict line-to-line voltage waveforms at both ends of the connection cable 3 shown in Fig. 1.

Replace the paragraph beginning at page 2, line 16 with:

Fig. 2-(1)2A depicts a case where an inverter-end line-to-line voltage Vuv_inv is varied stepwise as Vdc→0→Vdc. At this time, when a pulse width in voltage change coincides with half of a resonant cycle, as shown in Fig. 2-(2)2B, a motor-end line-to-line voltage Vuv_motor becomes three times as high as the direct-current bus voltage Vdc at maximum.

Replace the paragraph beginning at page 2, line 23 with:

Also, Fig. $\frac{3\cdot(1)3A}{2}$ depicts a case where the inverter-end line-to-line voltage Vuv_inv is varied stepwise as $0 \rightarrow Vdc \rightarrow -Vdc \rightarrow 0$. At this time, as shown in Fig. $\frac{3\cdot(2)3B}{2}$, the motorend line-to-line voltage Vuv_motor becomes four times as high as the direct-current bus voltage Vdc at maximum.

Replace the paragraph beginning at page 3, line 2 with:

From the description with reference to Figs. 2 and 32A to 3B, it is known that if the pulse width in voltage change is sufficiently large, after resonance occurring due to a stepwise voltage change is attenuated, the next stepwise voltage change is applied, and therefore a surge voltage exceeding twice the direct-current bus voltage Vdc does not occur.

Replace the paragraph beginning at page 4, line 20 with:

It is an object of the present invention to solve at least the above problems in the conventional technology. An apparatus according to one aspect of the present invention, which is for controlling a power converter in which an output voltage is controlled by a

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Replace the paragraph beginning at page 49, line 9 with:

Next, with reference to Fig. 24 Figs. 24A to 24C, a method of calculating the error Err is described. In Fig. 24 (1)24A, loci A and B of magnetic flux vectors for two PWM control cycles before voltage vector adjustment are shown. The locus A is in the previous cycle, while the locus B is the current cycle. In Fig. 24 (2)24B, loci A' and B' of magnetic flux vectors after voltage vector adjustment are shown. As a result of ensuring the minimum zero-voltage-vector output time with the locus A of the magnetic flux vectors at the previous time, it becomes the locus A' with its length being shortened. Fig. 24 (3)24C is drawn by overlaying (1) Fig. 24A and (2) of Fig. 24 each other on Fig. 24B.

Replace the paragraph beginning at page 49, line with:

Here, consider the case where the end point of the locus of the magnetic flux vectors before adjustment is made to agree with that after adjustment by drawing a locus as shown in the locus B' in the present PWM control cycle. As has been described in the first embodiment (Fig. 10); (Figs. 10A to 10C), when the voltage vectors are adjusted according to equation 3 so that the relative ratio of the output times of the voltage vectors other than the zero-voltage vectors is unchanged, a triangle of the locus A is similar to a triangle of the locus A'. Similarly, a triangle of the locus B is similar to a triangle of the locus B'.

Delete the paragraph beginning at page 51, line 7:

Eighth Embodiment

Replace the paragraph beginning at page 51, line 21 with:

That is, taking note of Fig. 12(1)12A, eliminating the zero-voltage vector V7 does not pose the line-to-line voltages Vvw and Vwu. However, as for the line-to-line voltage Vuv, two pulses of the voltage vector V1 are present over the voltage vector V2. This corresponds to the case of (1-2) of Fig. 14 Fig. 14B, with the voltage vector V2 being replaced by the zero-voltage vector. That is, when the output time of the zero-voltage vector is adjusted to zero, depending on the non-zero-voltage-vector output time, a surge voltage may occur. In such a case, in the eight eighth embodiment, the concept of ensuring the minimum zero-voltage-vector output time is applied. Hereinafter, a description is made implied according to